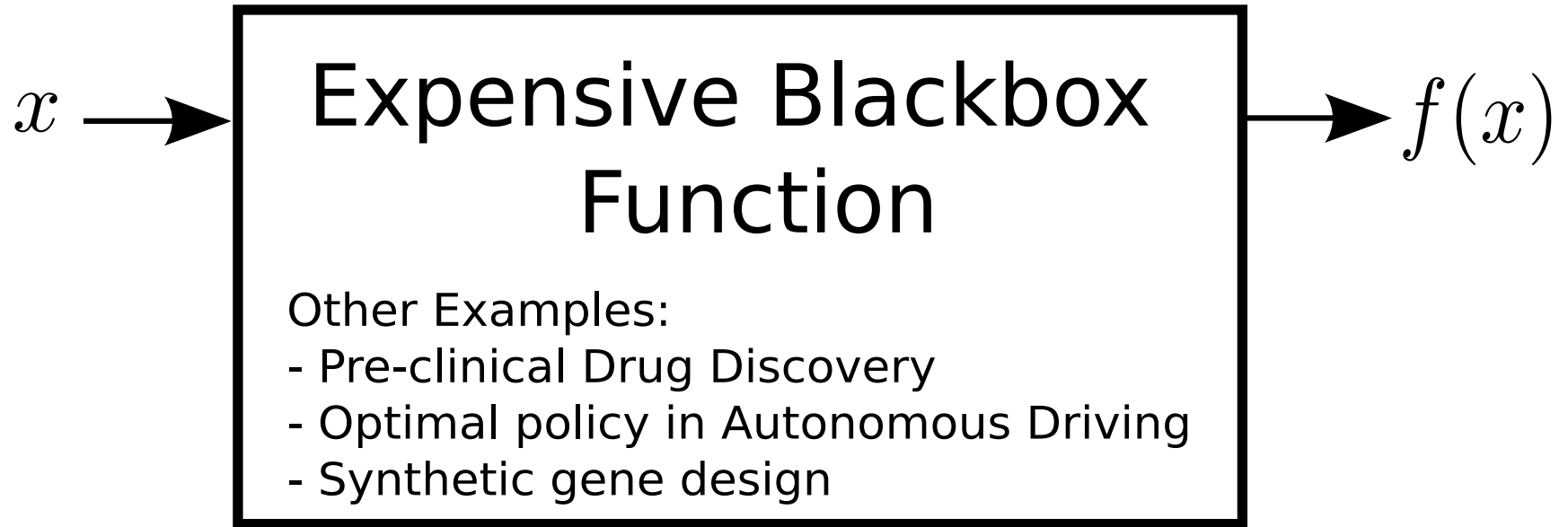


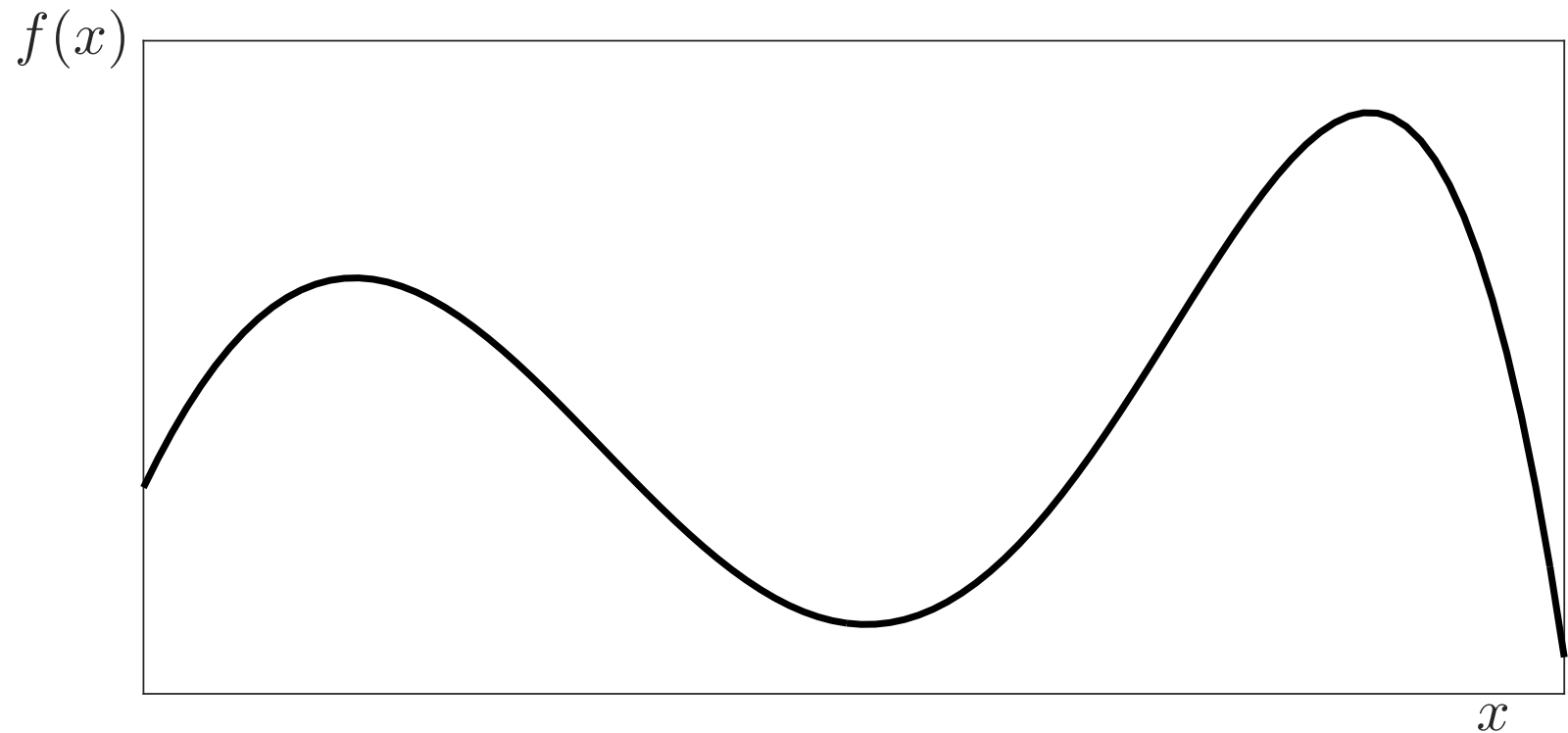
Brief Overview of Bayesian Optimization and Gaussian Process

Black-box Optimisation



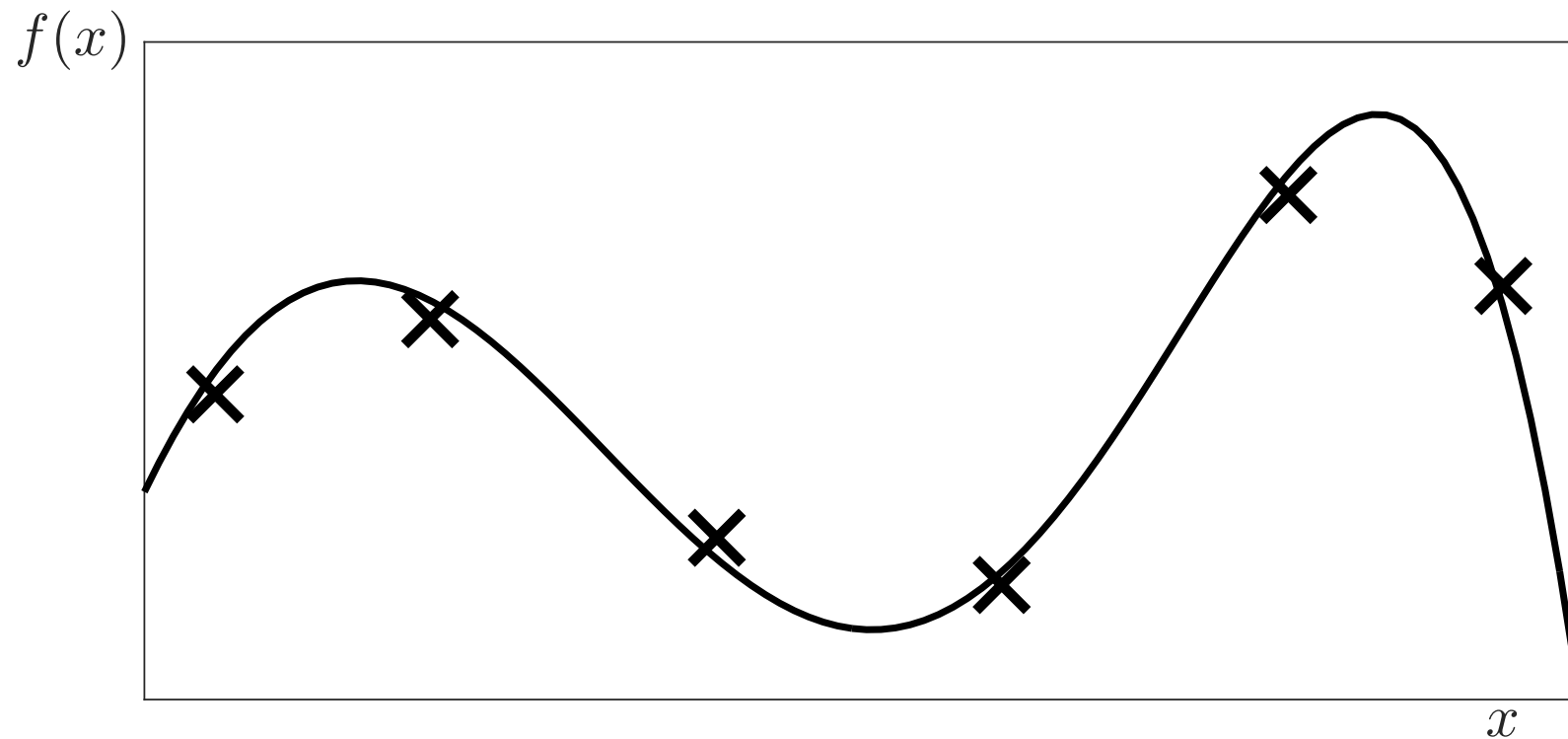
Black-box Optimisation

$f : \mathcal{X} \rightarrow \mathbb{R}$ is an expensive, black-box function, accessible only via noisy evaluations.



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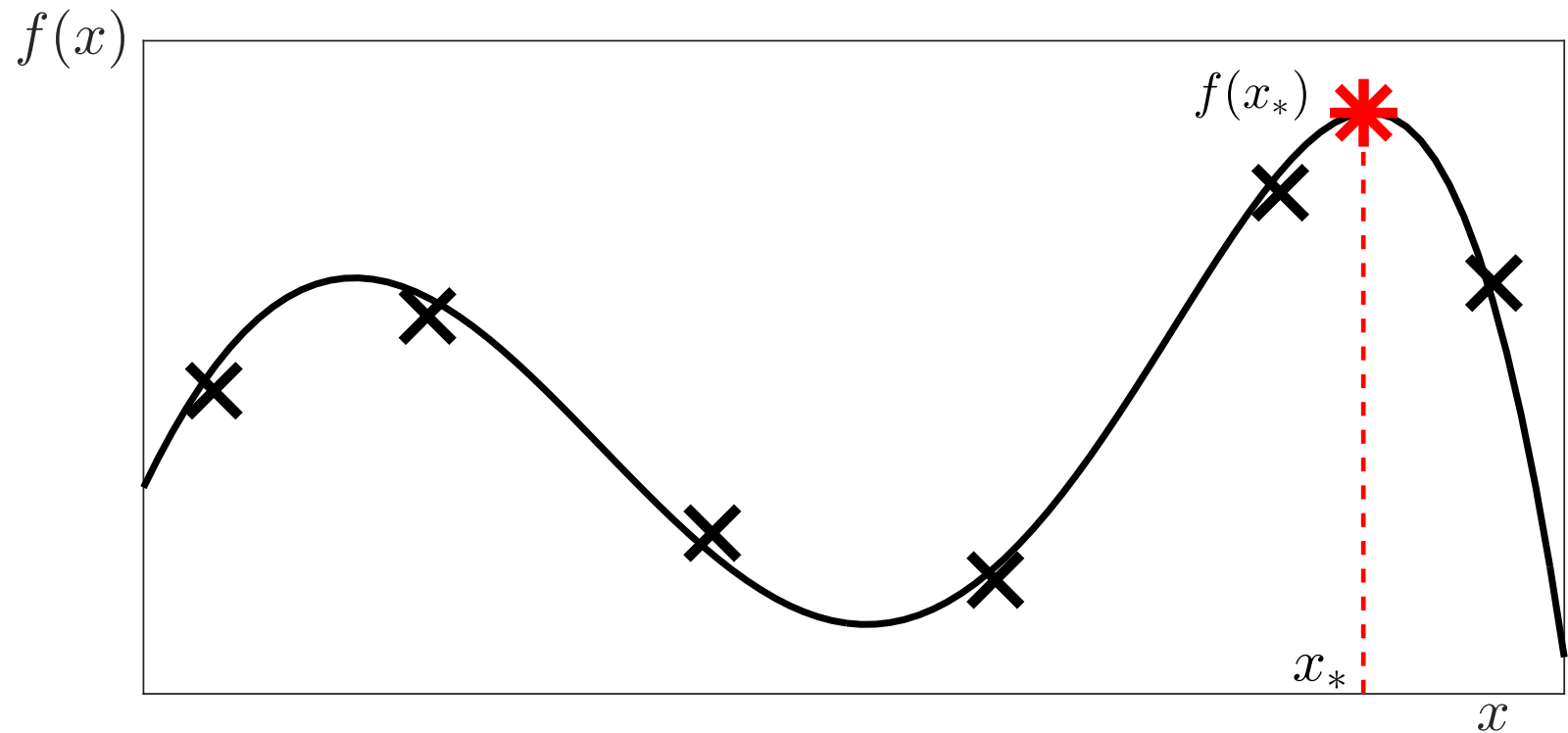
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Let $x_* = \operatorname{argmax}_x f(x)$.



Bayesian Models for f

e.g. Gaussian Processes (\mathcal{GP})

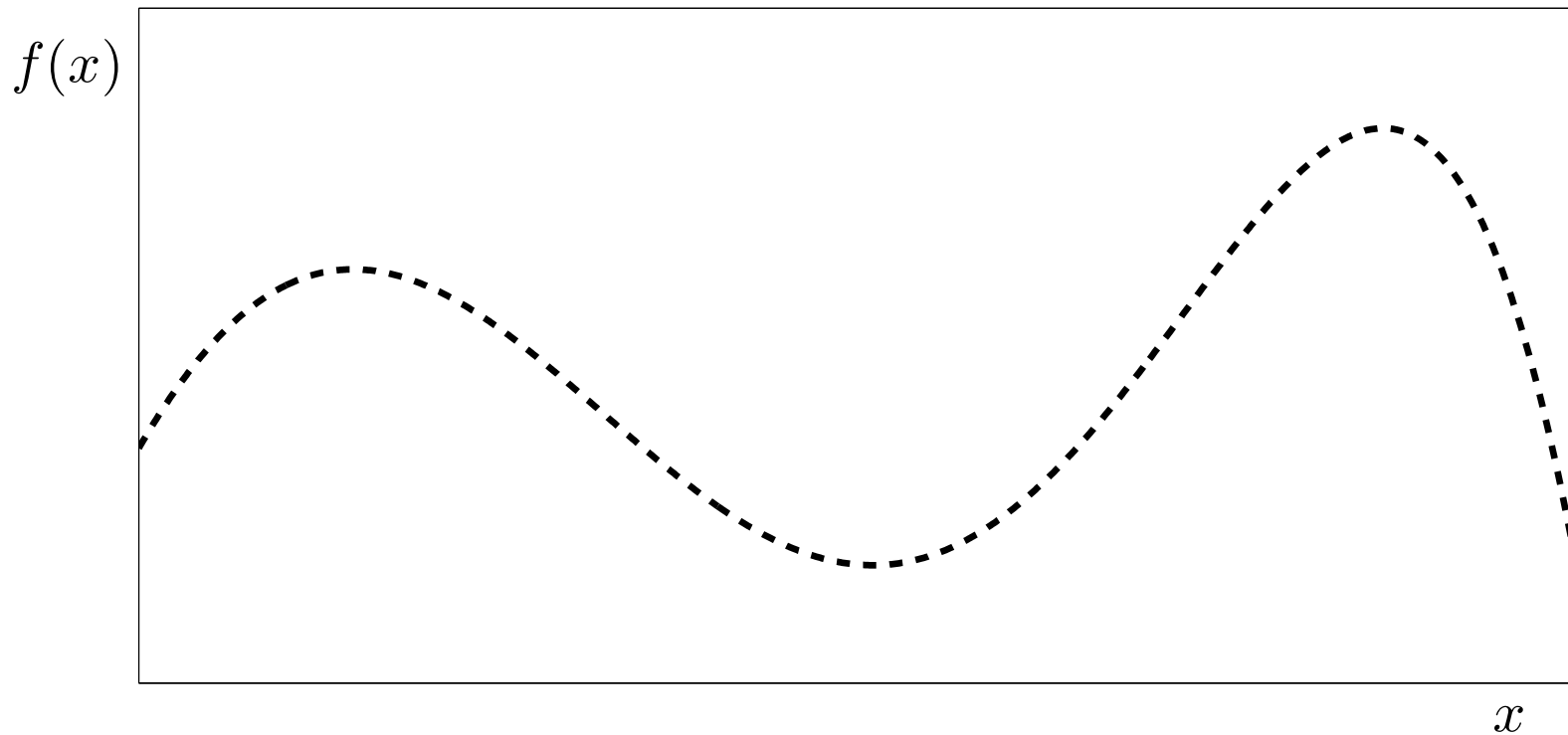
\mathcal{GP} : A distribution over functions from \mathcal{X} to \mathbb{R} .

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Functions with no observations

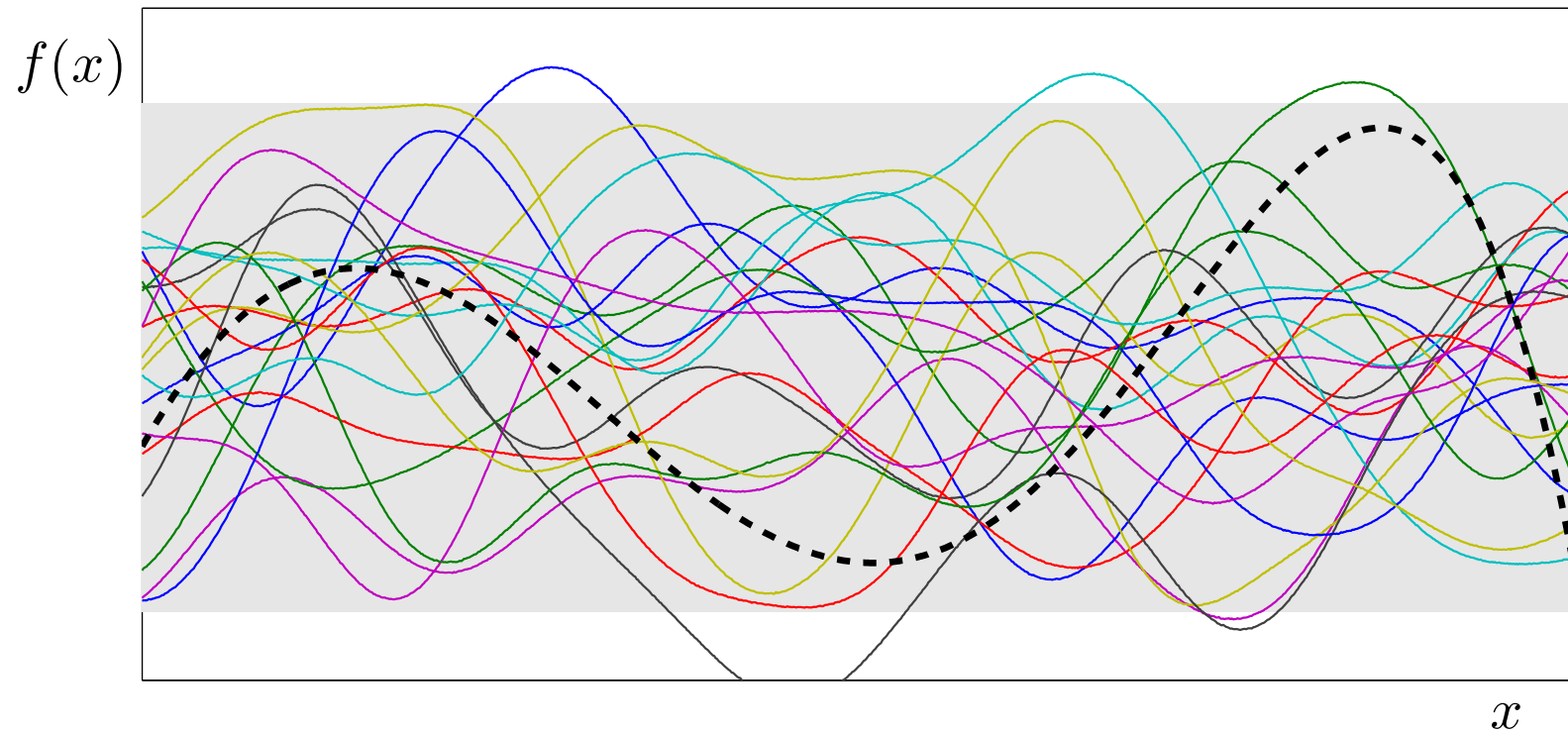


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Prior \mathcal{GP}

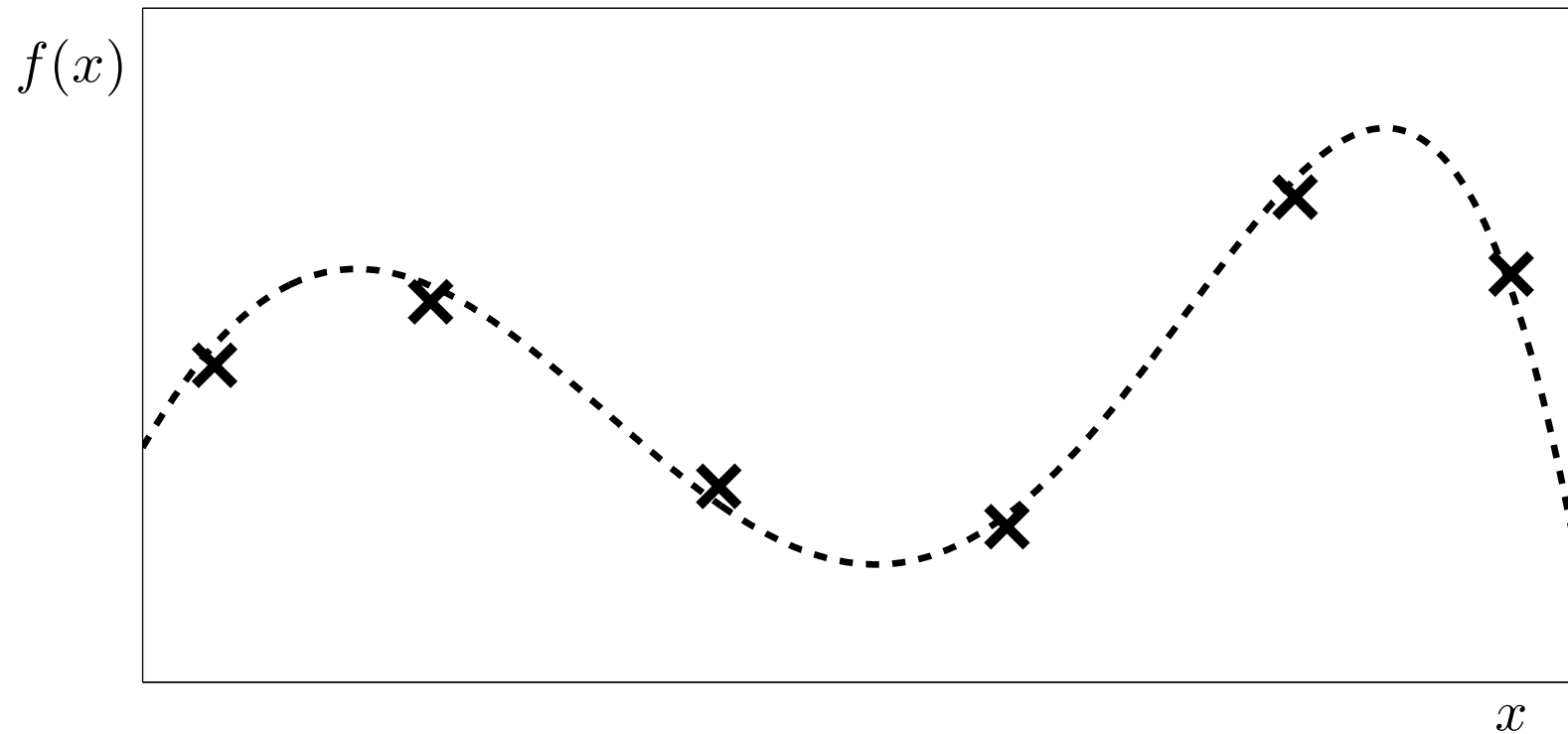


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Observations

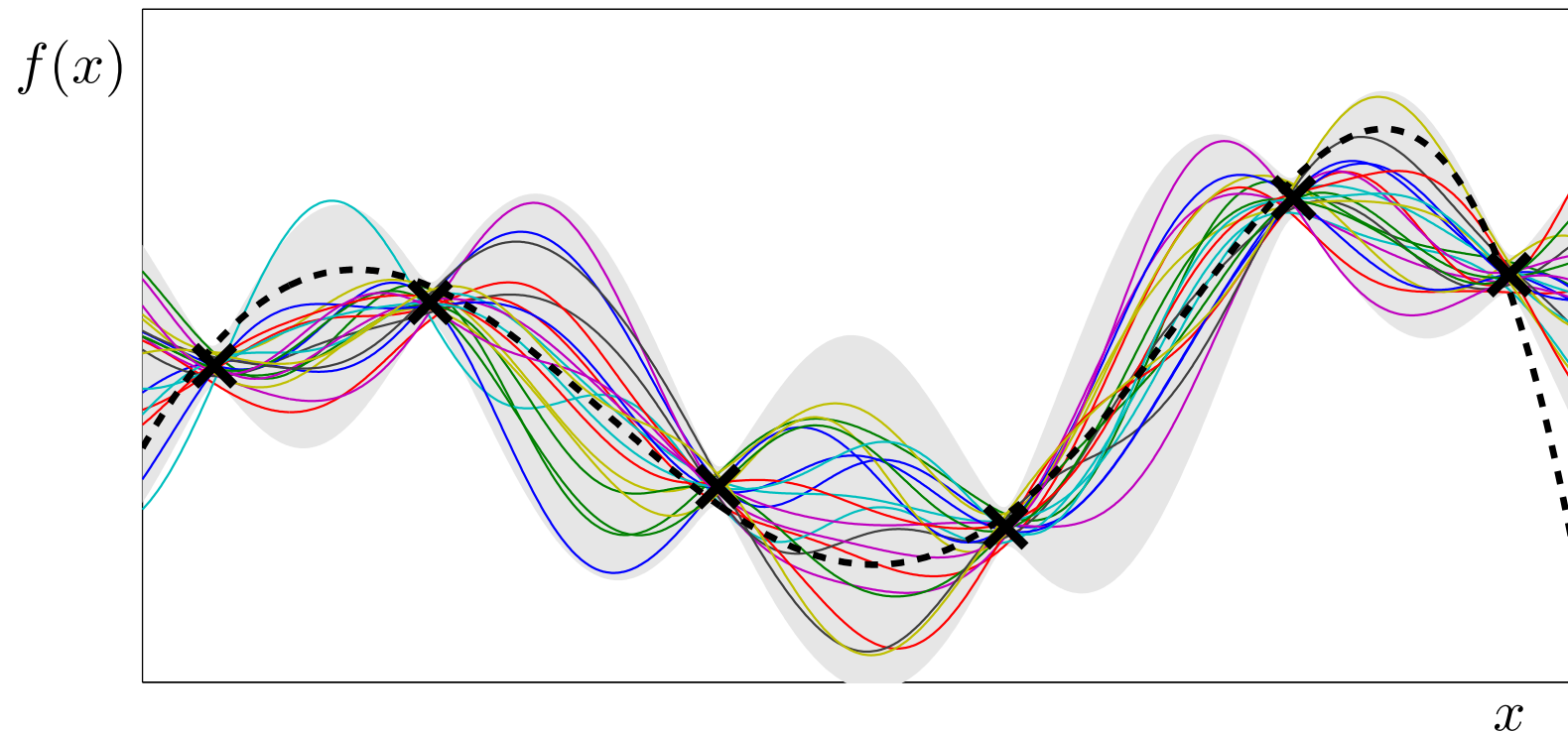


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Posterior \mathcal{GP} given observations

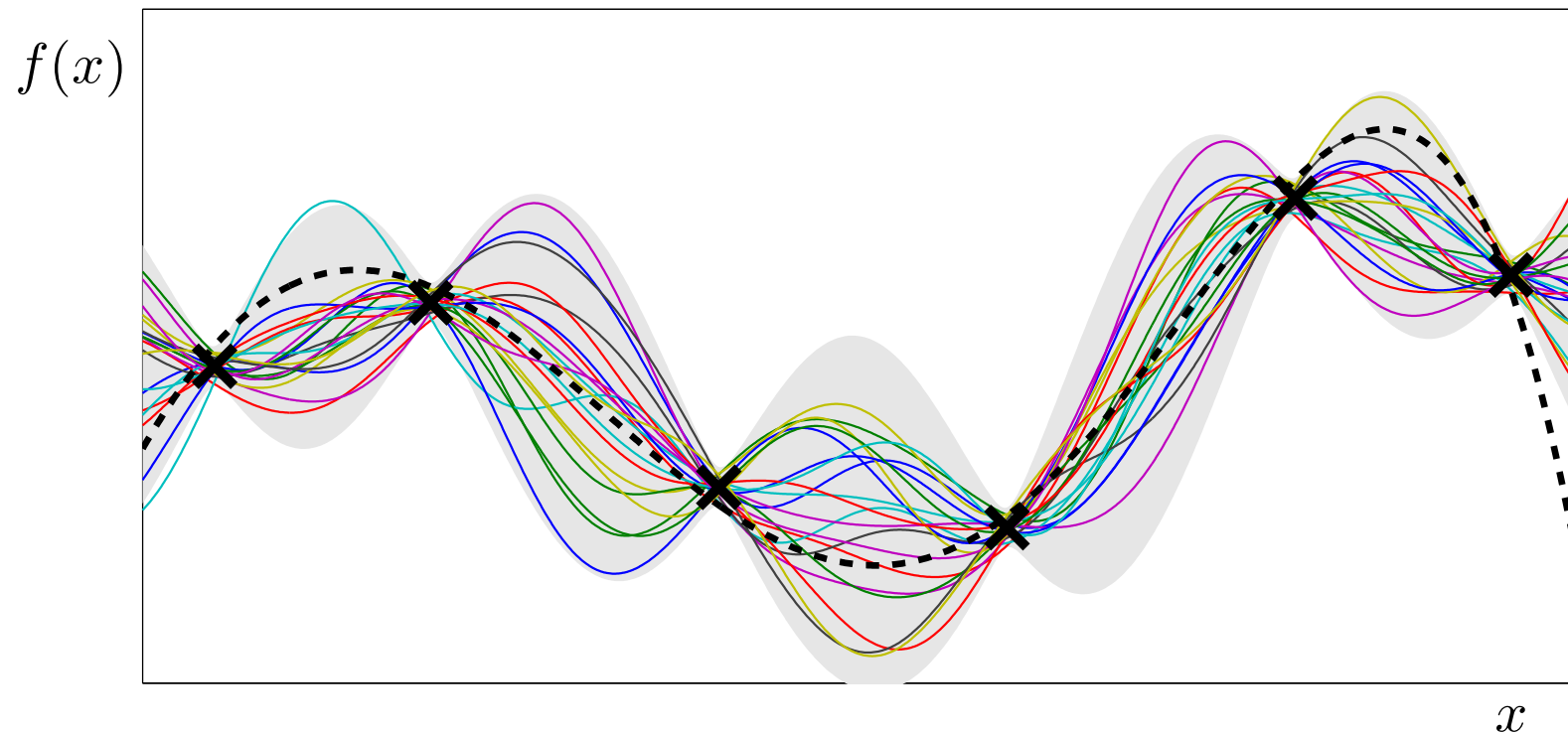


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After t observations, $f(x) \sim \mathcal{N}(\mu_t(x), \sigma_t^2(x))$.

Mathematical Foundations: Definition

Gaussian process = generalization of multivariate Gaussian distribution to infinitely many variables.

Definition: a Gaussian process is a collection of random variables, any finite number of which have (consistent) Gaussian distributions.

A Gaussian distribution is fully specified by a mean vector, μ , and covariance matrix Σ :

$$\mathbf{f} = (f_1, \dots, f_n) \sim \mathcal{N}(\mu, \Sigma), \text{ indices } i = 1, \dots, n$$

A Gaussian process is fully specified by a mean function $m(\mathbf{x})$ and covariance function $K(\mathbf{x}, \mathbf{x}')$:

$$f(\mathbf{x}) \sim \mathcal{GP}(m(\mathbf{x}), K(\mathbf{x}, \mathbf{x}')), \text{ indices } \mathbf{x}$$

Gaussian Processes

– Noise free observations

- Model

- (x, f) are the observed locations and values (training data)
- (x^*, f^*) are the test or prediction data locations and values.

$$\begin{bmatrix} \mathbf{f} \\ \mathbf{f}_* \end{bmatrix} \sim \mathcal{N} \left(\mathbf{0}, \begin{bmatrix} K(X, X) & K(X, X_*) \\ K(X_*, X) & K(X_*, X_*) \end{bmatrix} \right)$$

- After observing some noise free data (x, f) ,

$$\mathbf{f}_* | X_*, X, \mathbf{f} \sim \mathcal{N}(K(X_*, X)K(X, X)^{-1}\mathbf{f},$$

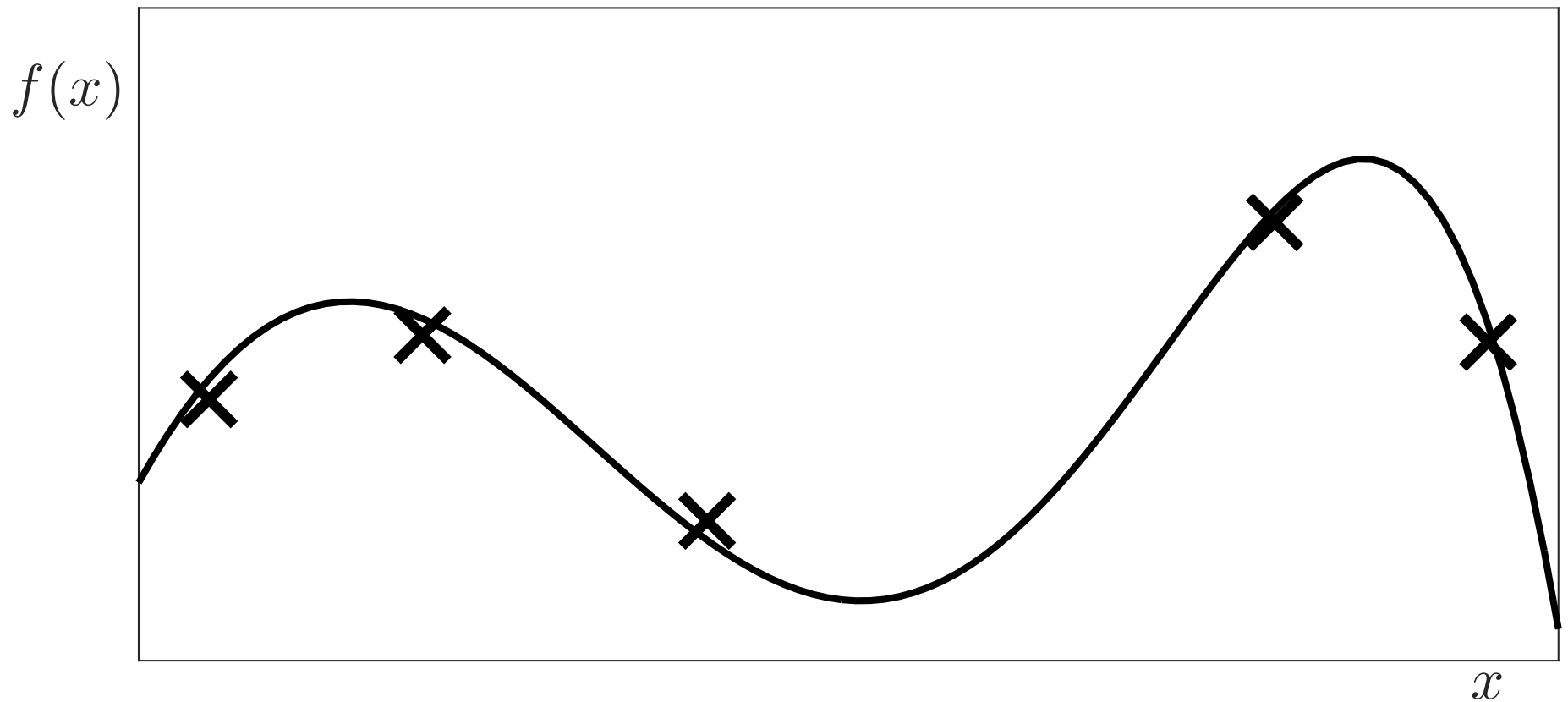
$$K(X_*, X_*) - K(X_*, X)K(X, X)^{-1}K(X, X_*))$$

Bayesian Optimisation with Upper Confidence Bounds

Model $f \sim \mathcal{GP}$.

Gaussian Process Upper Confidence Bound (GP-UCB)

(Srinivas et al. 2010)

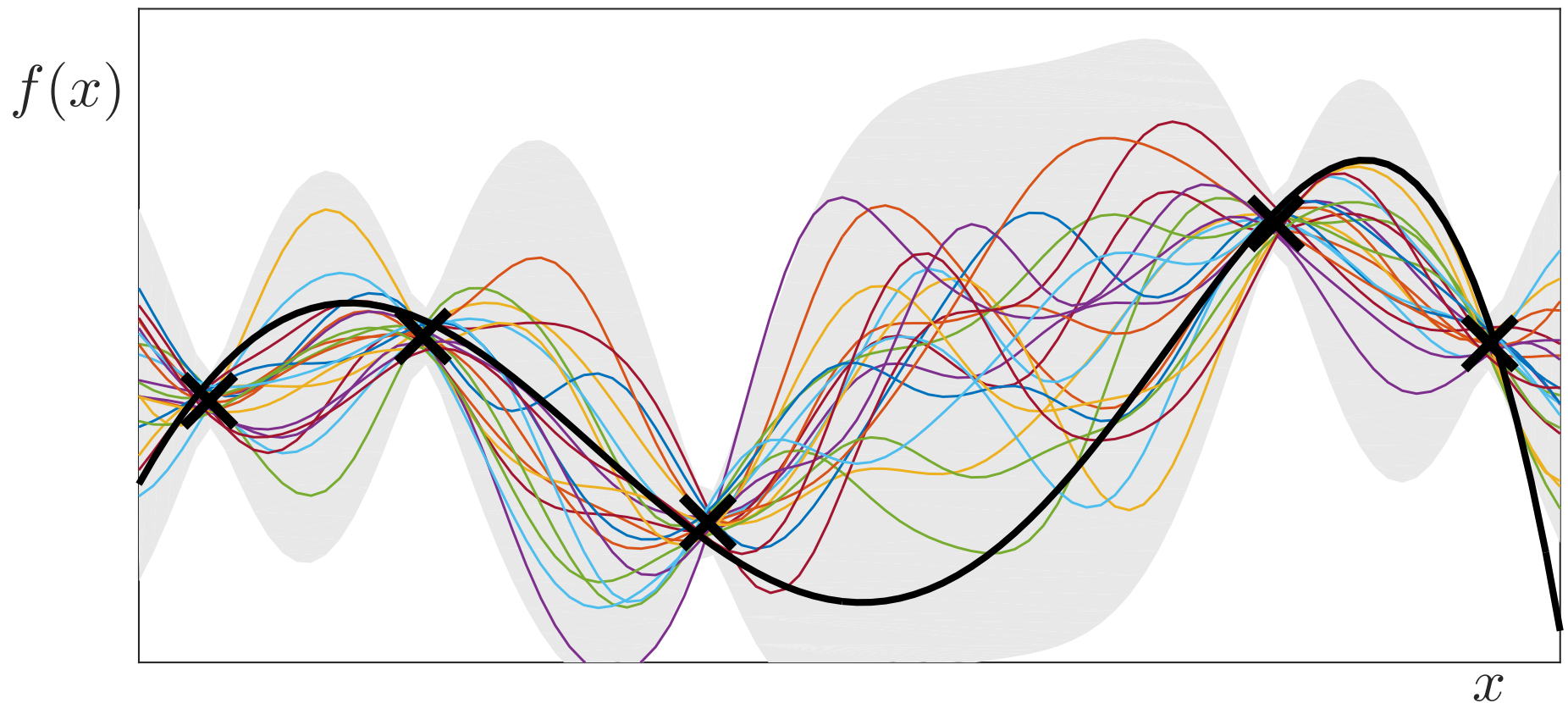


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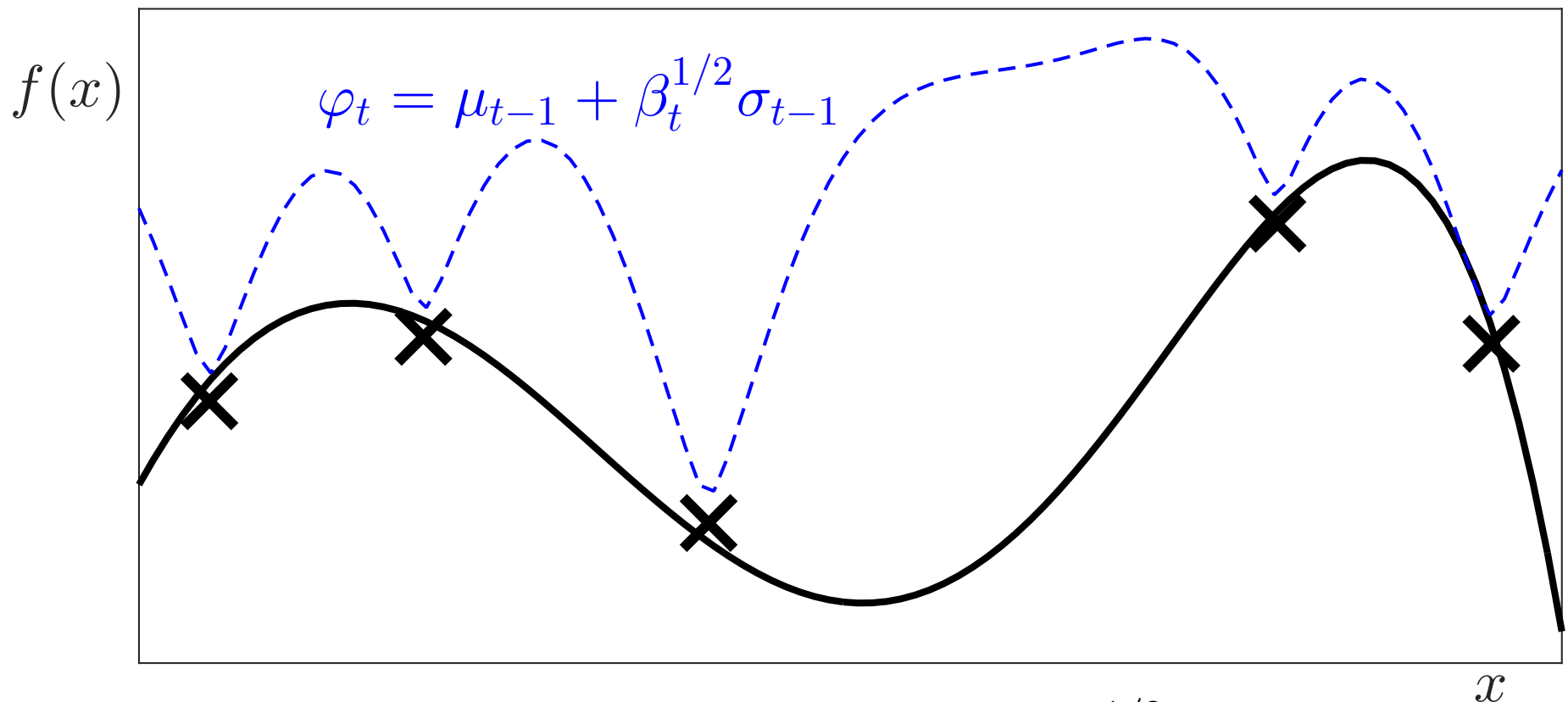
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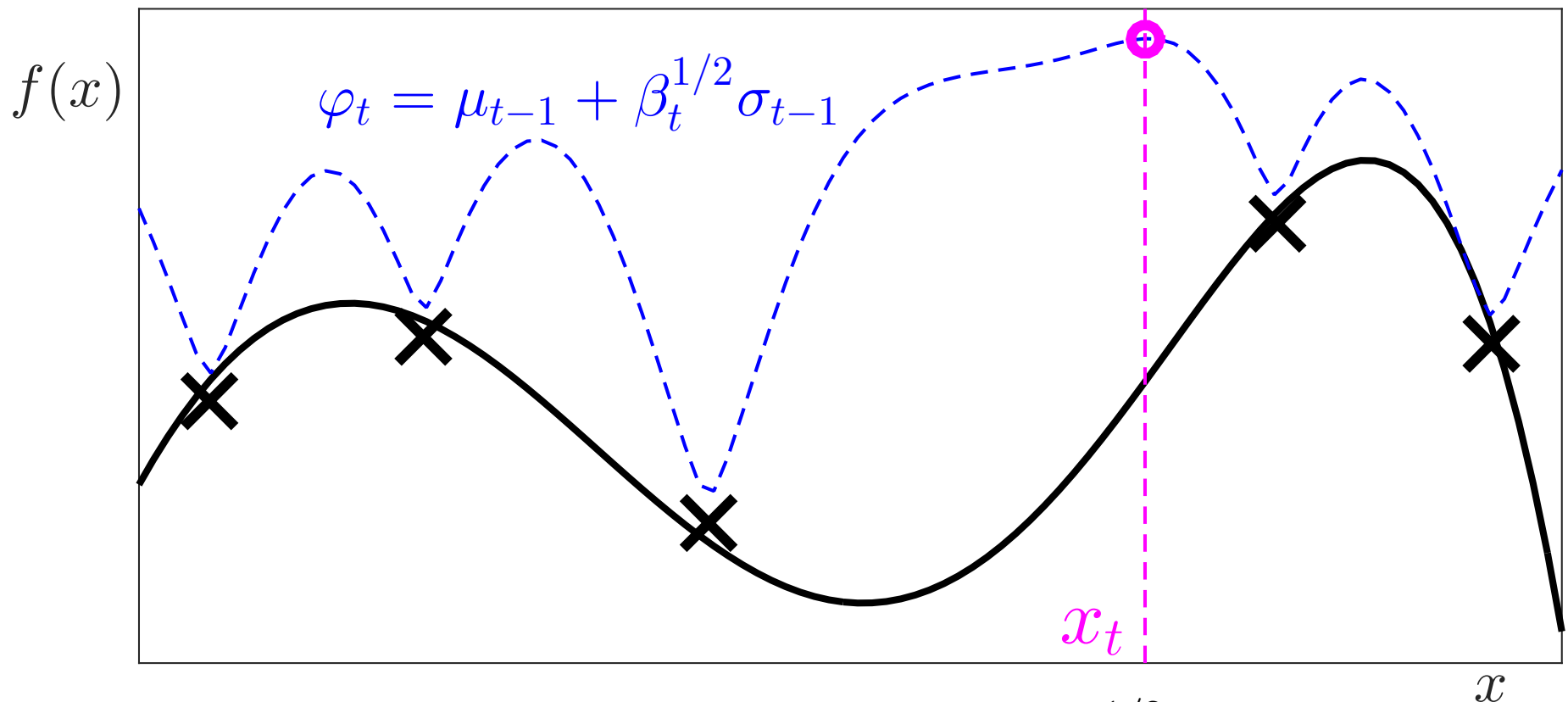
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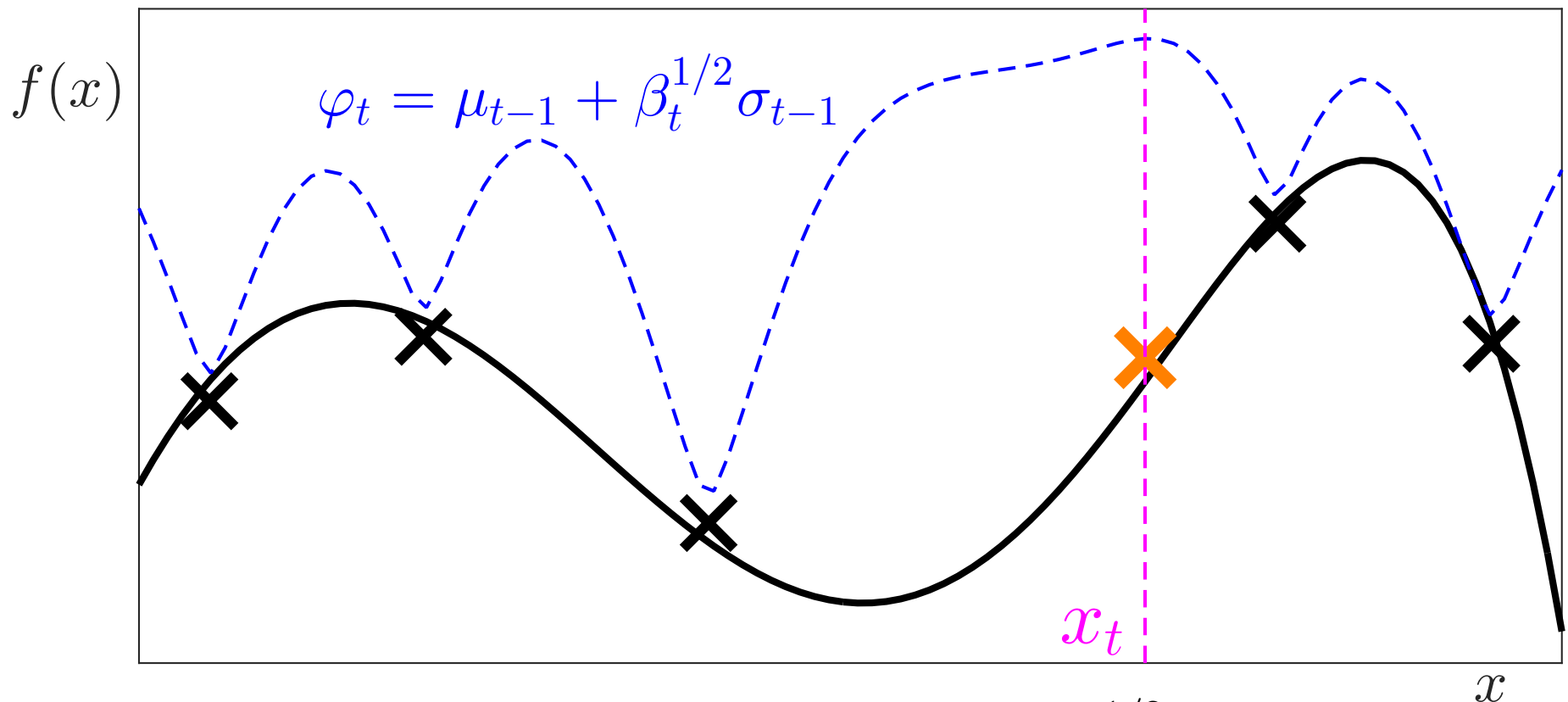
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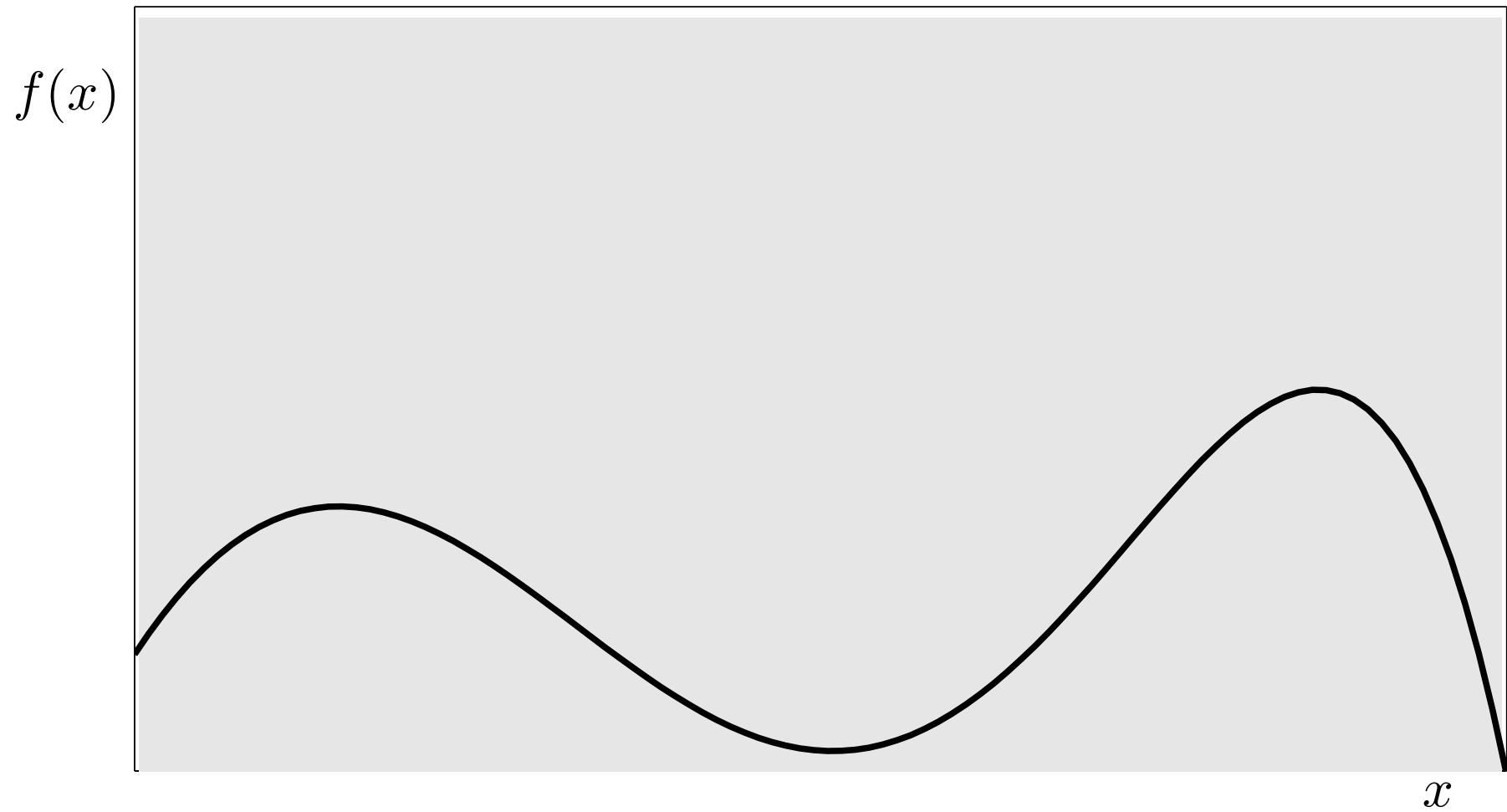
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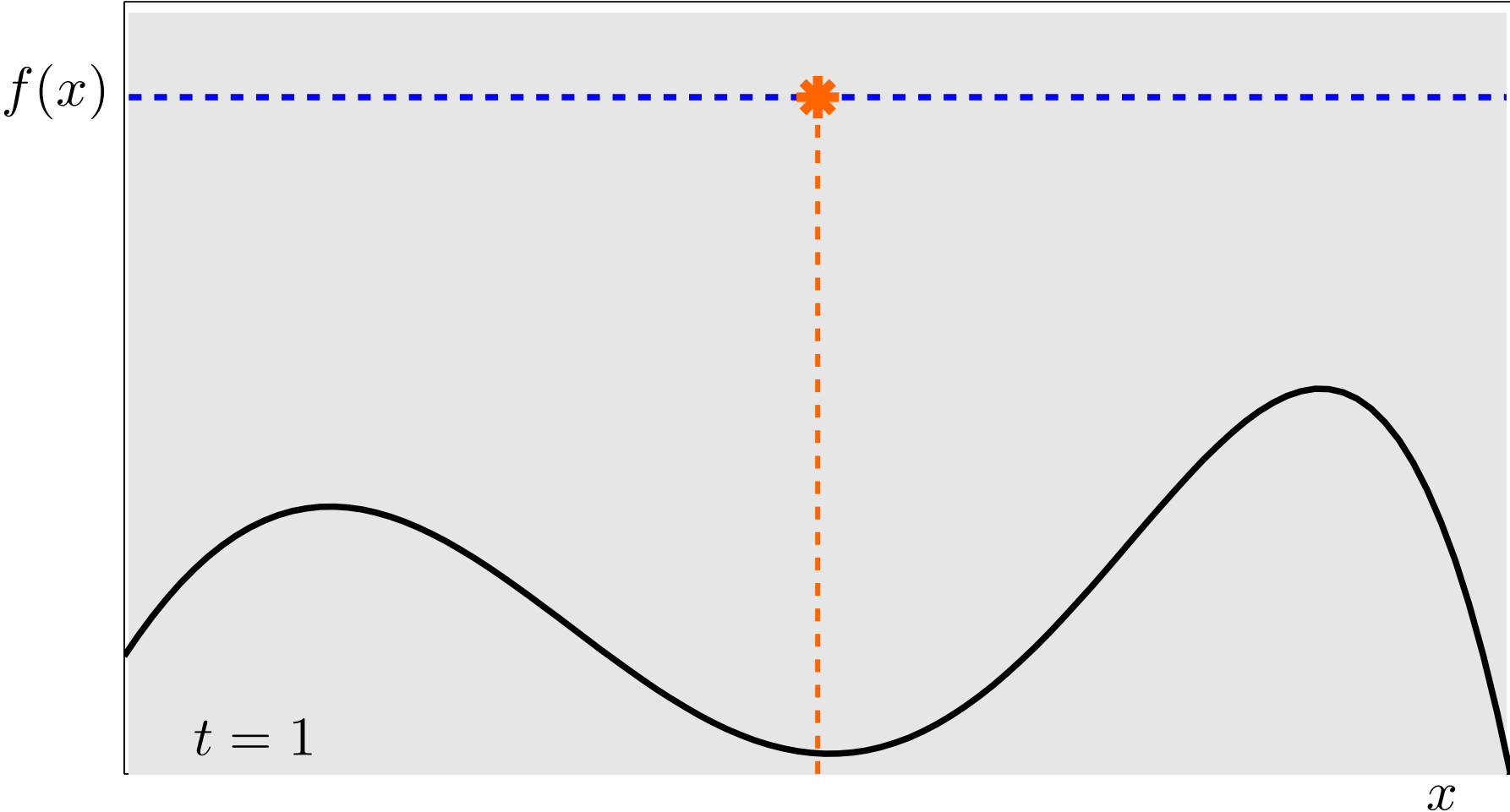
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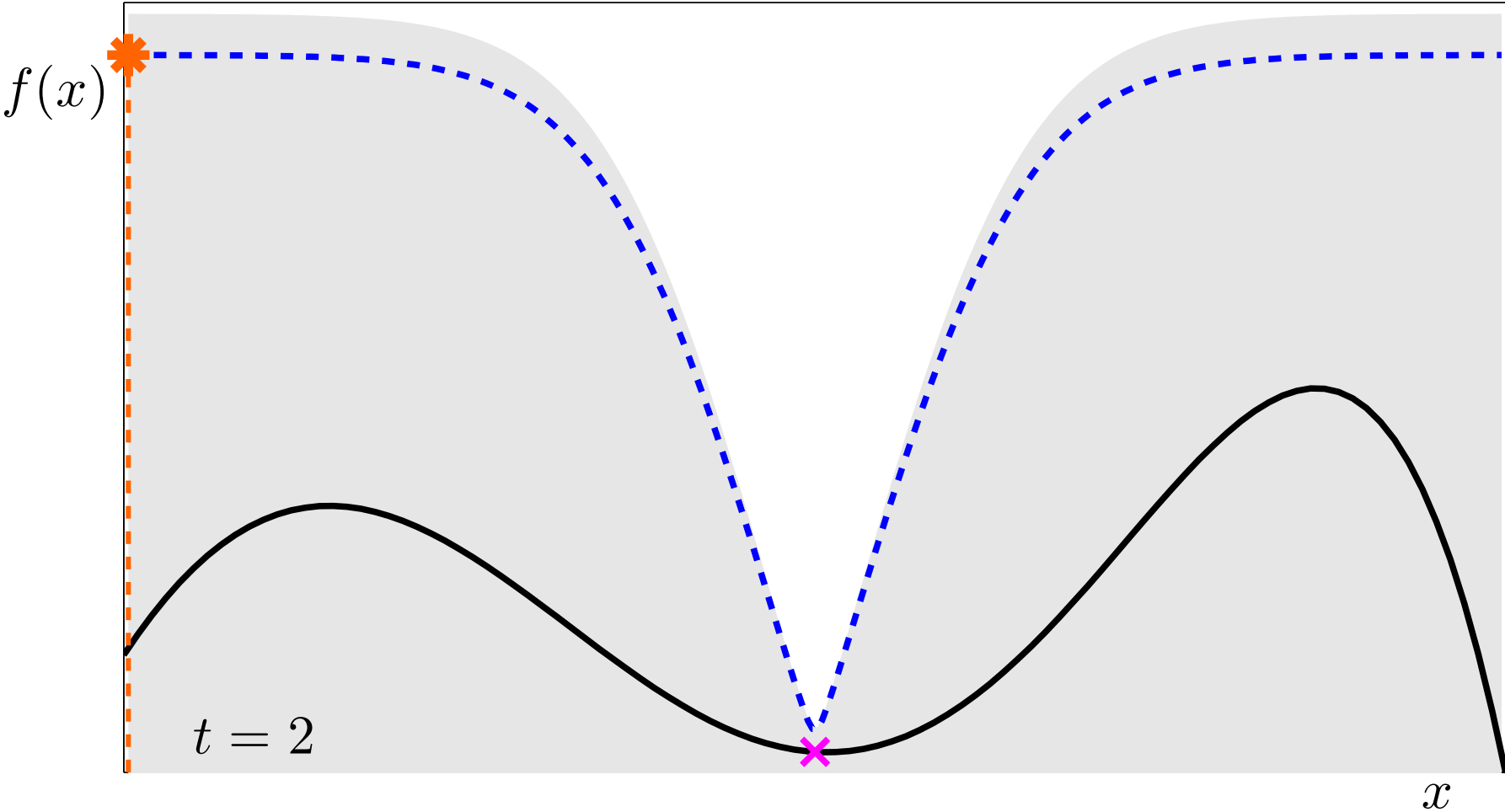
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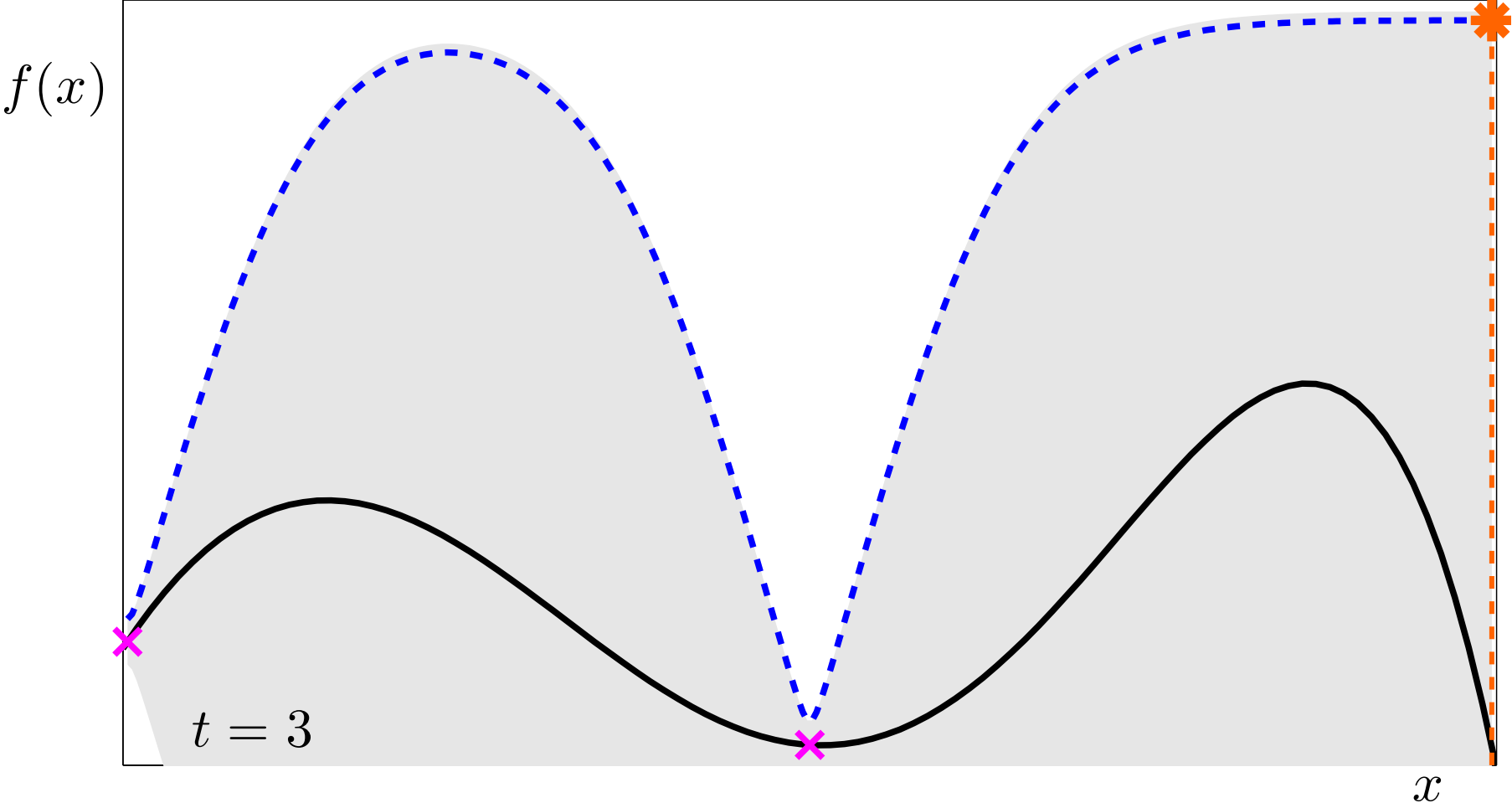
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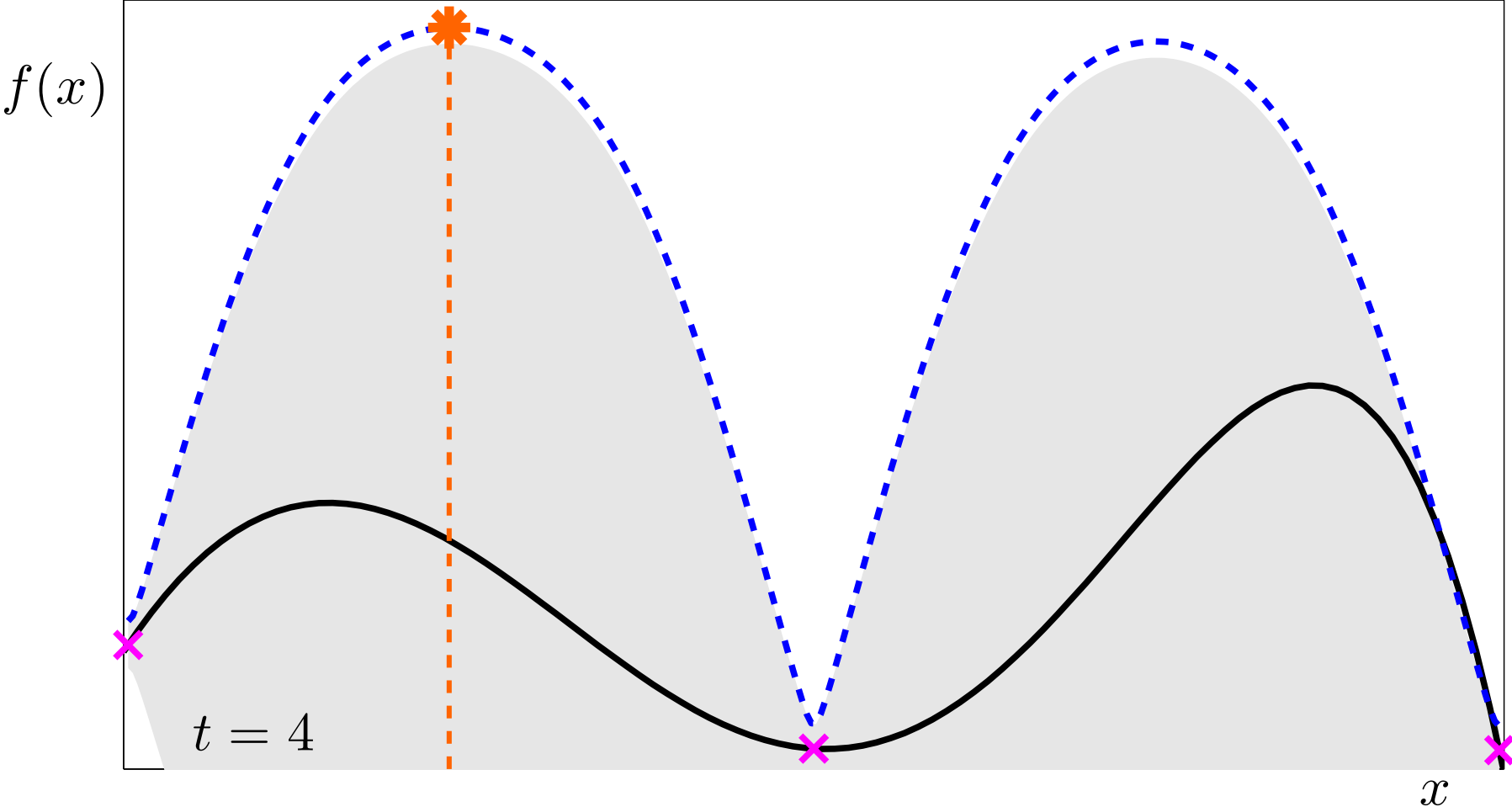
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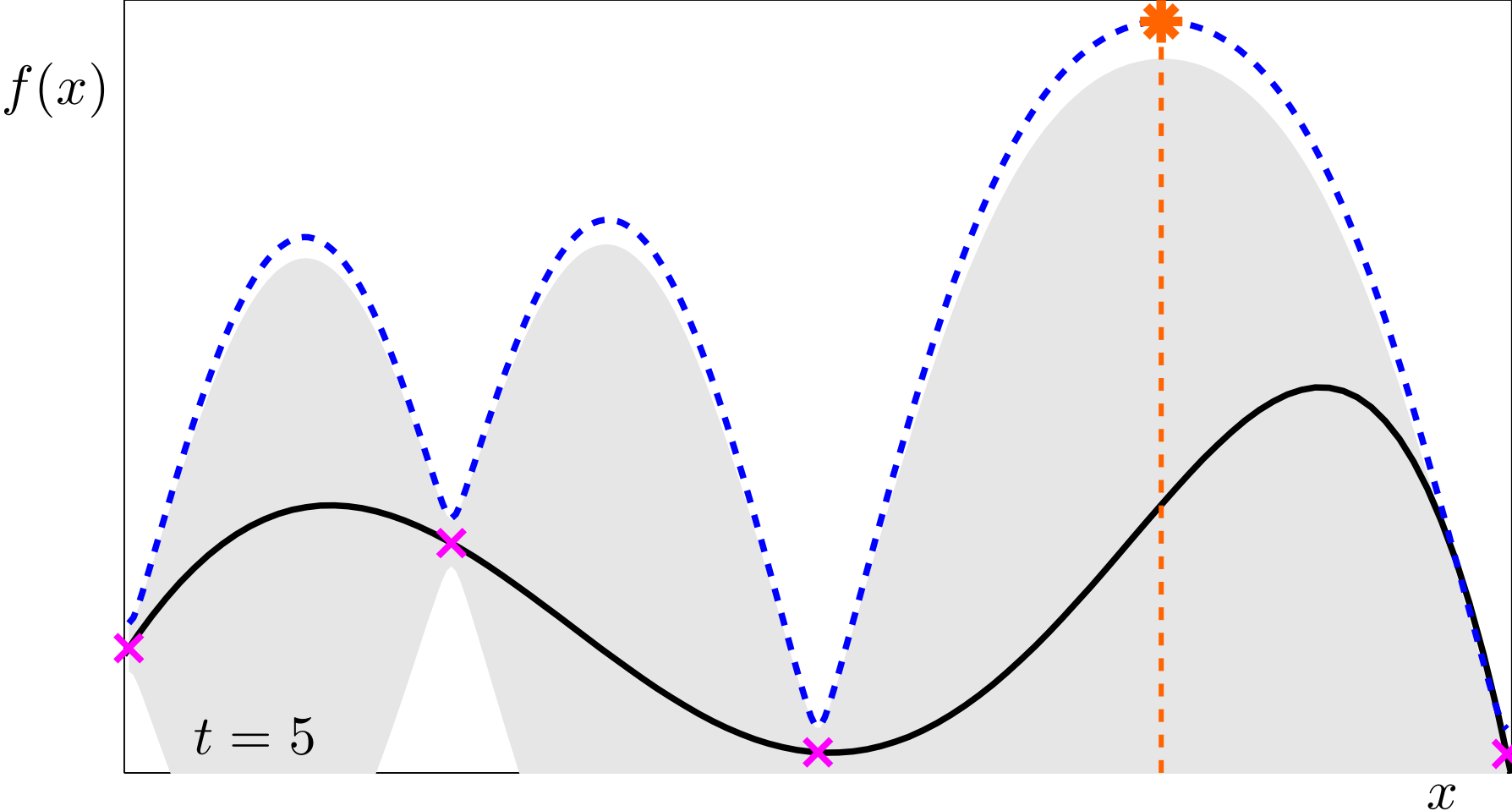
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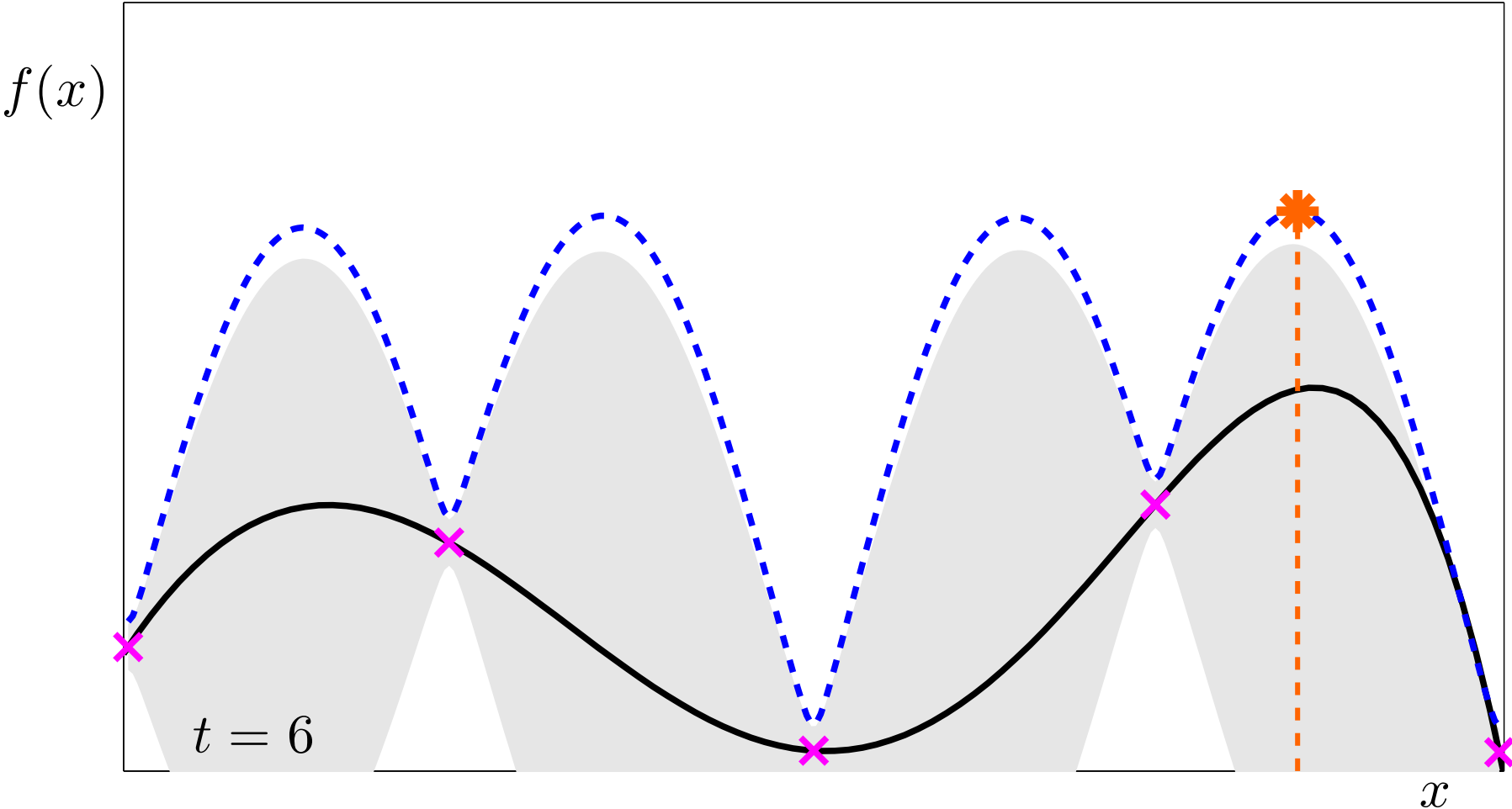
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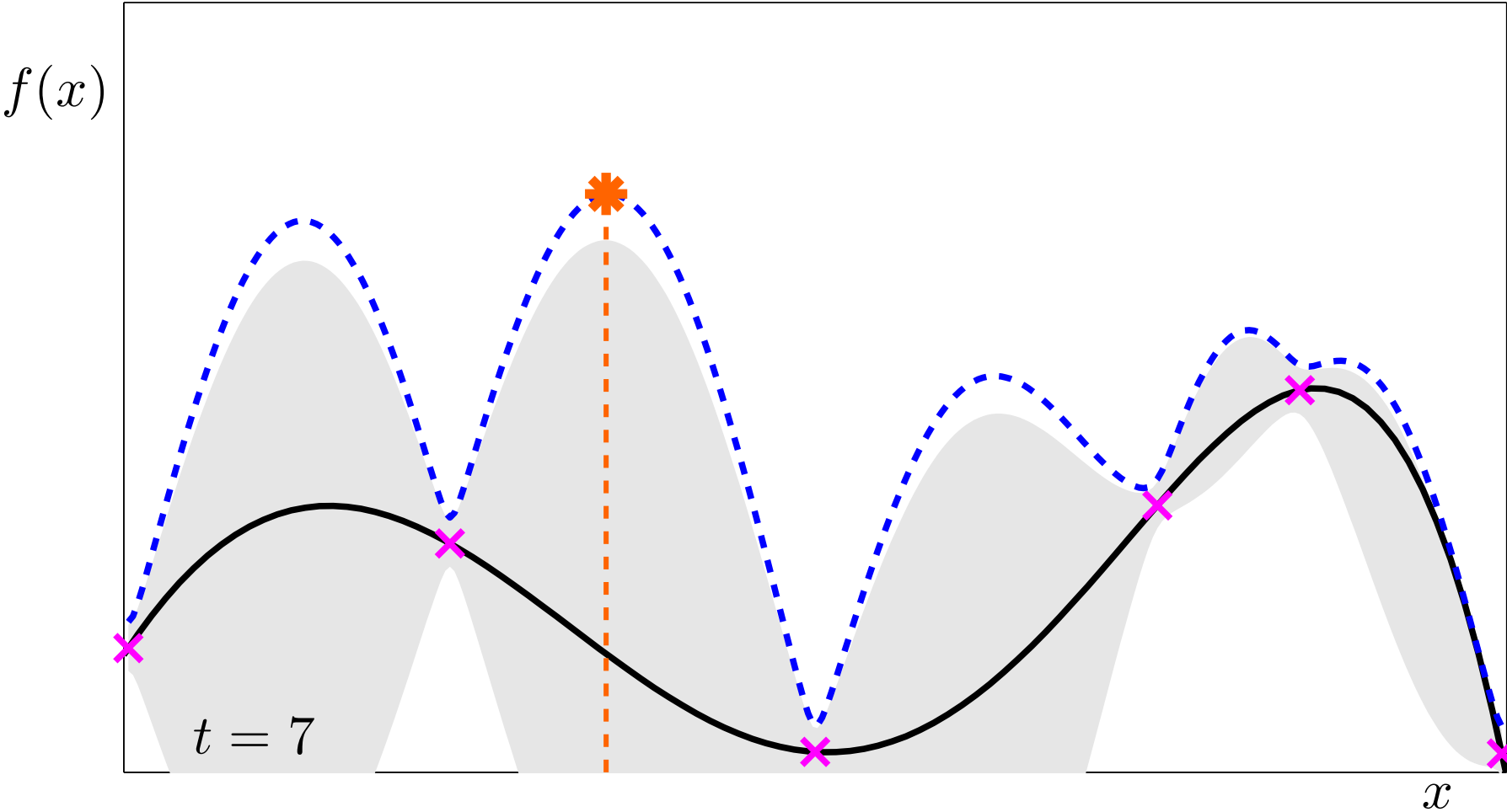
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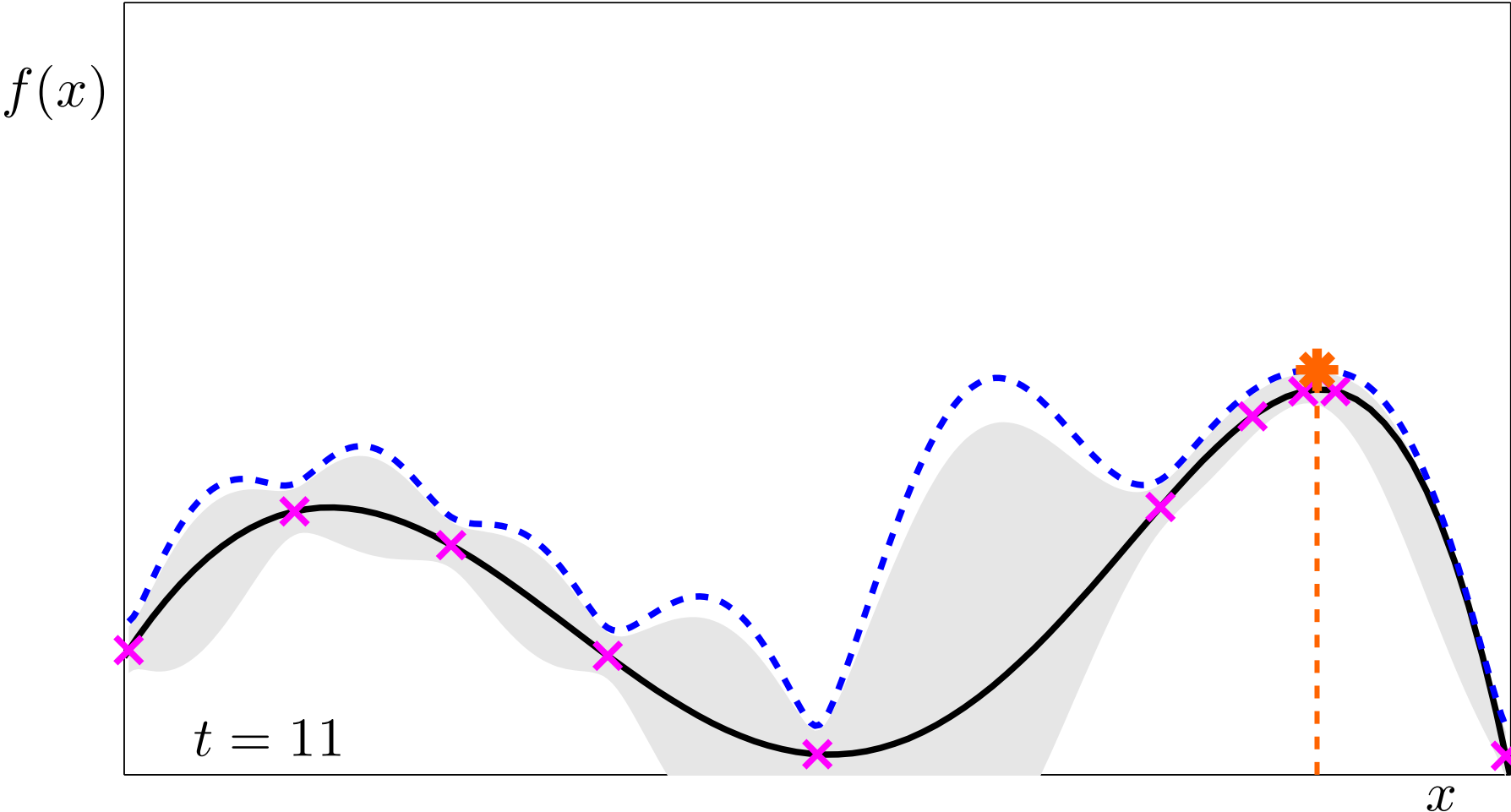
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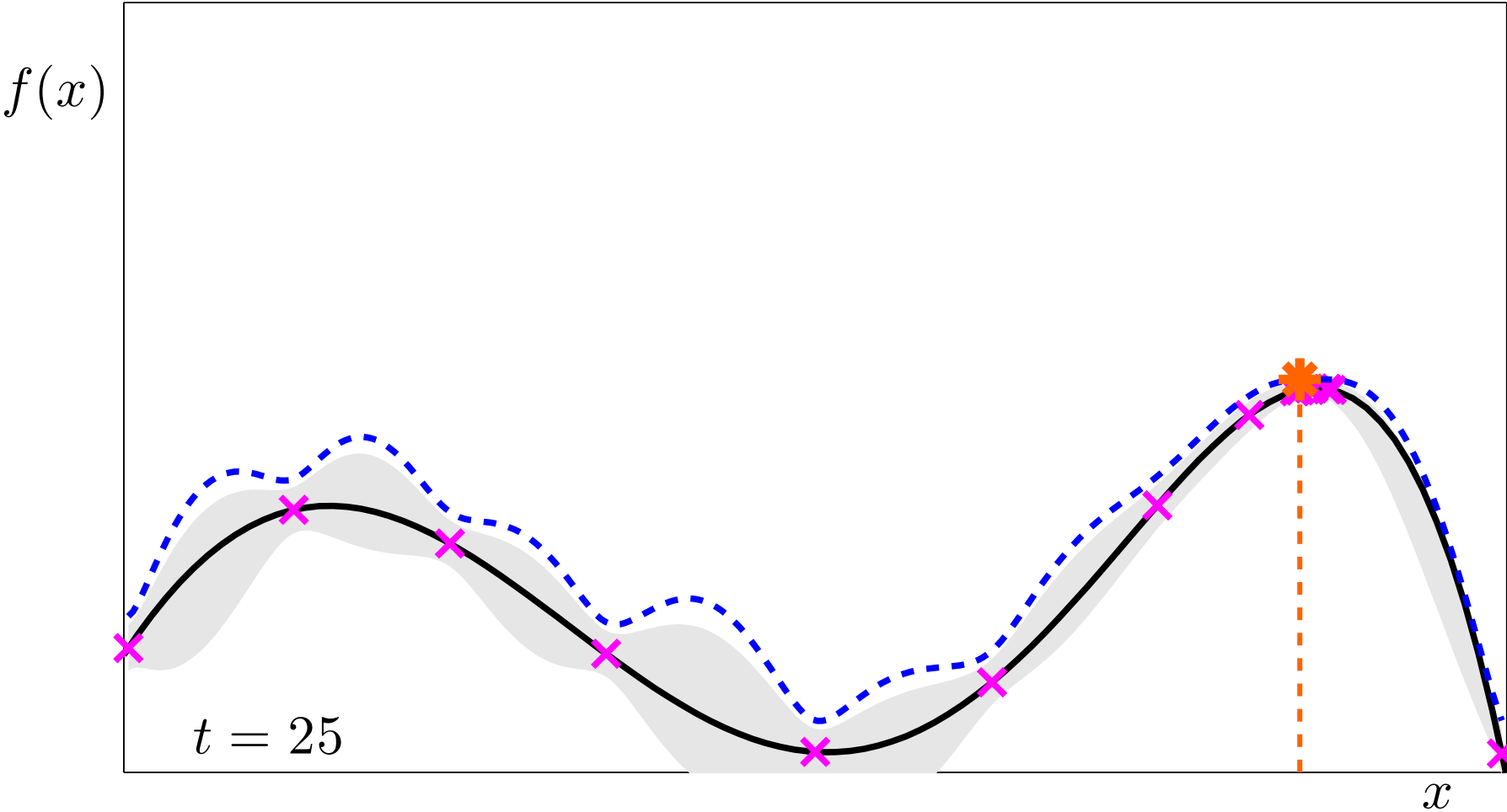
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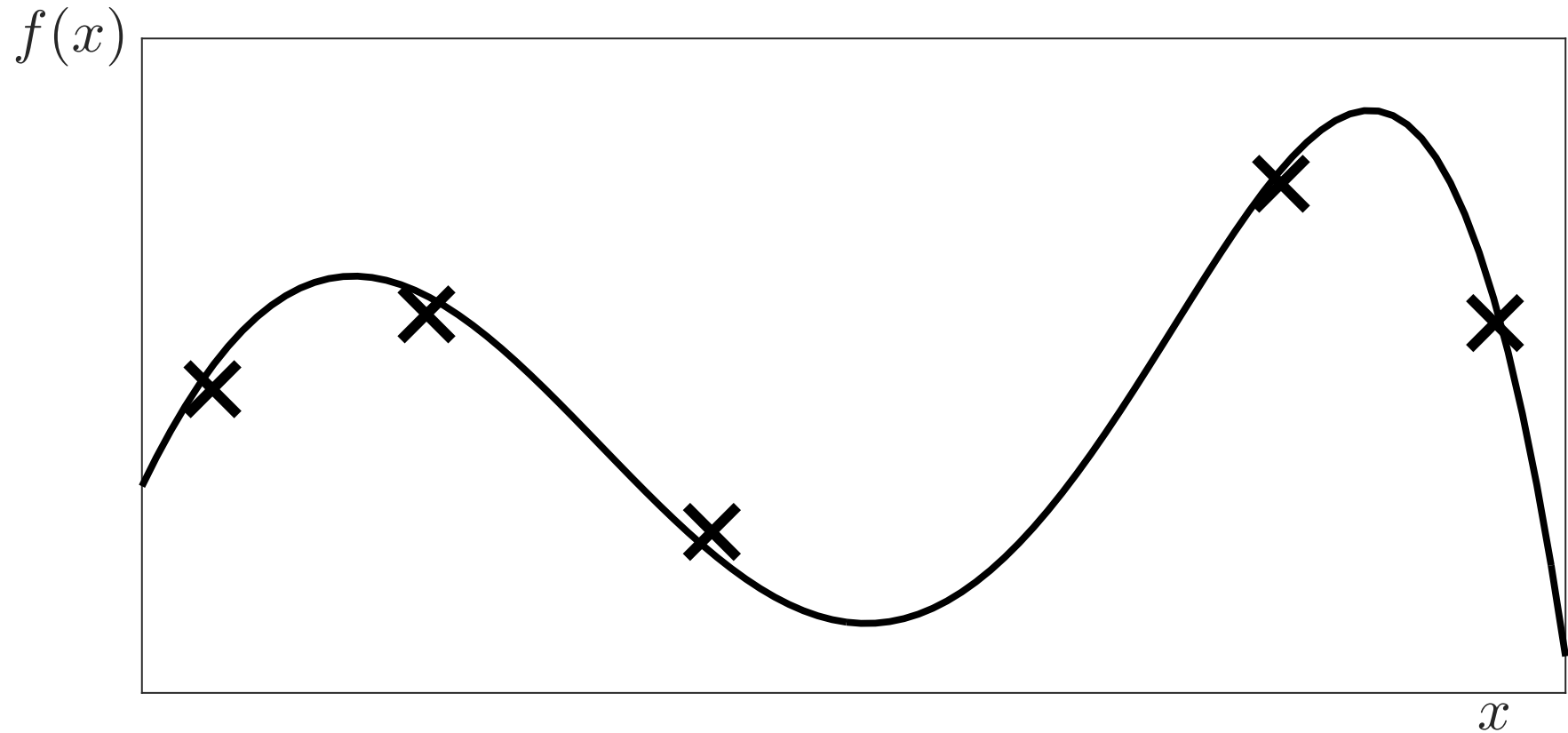


Bayesian Optimisation with Thompson Sampling

Model $f \sim \mathcal{GP}(\mathbf{0}, \kappa)$.

Thompson Sampling (TS)

(Thompson, 1933).

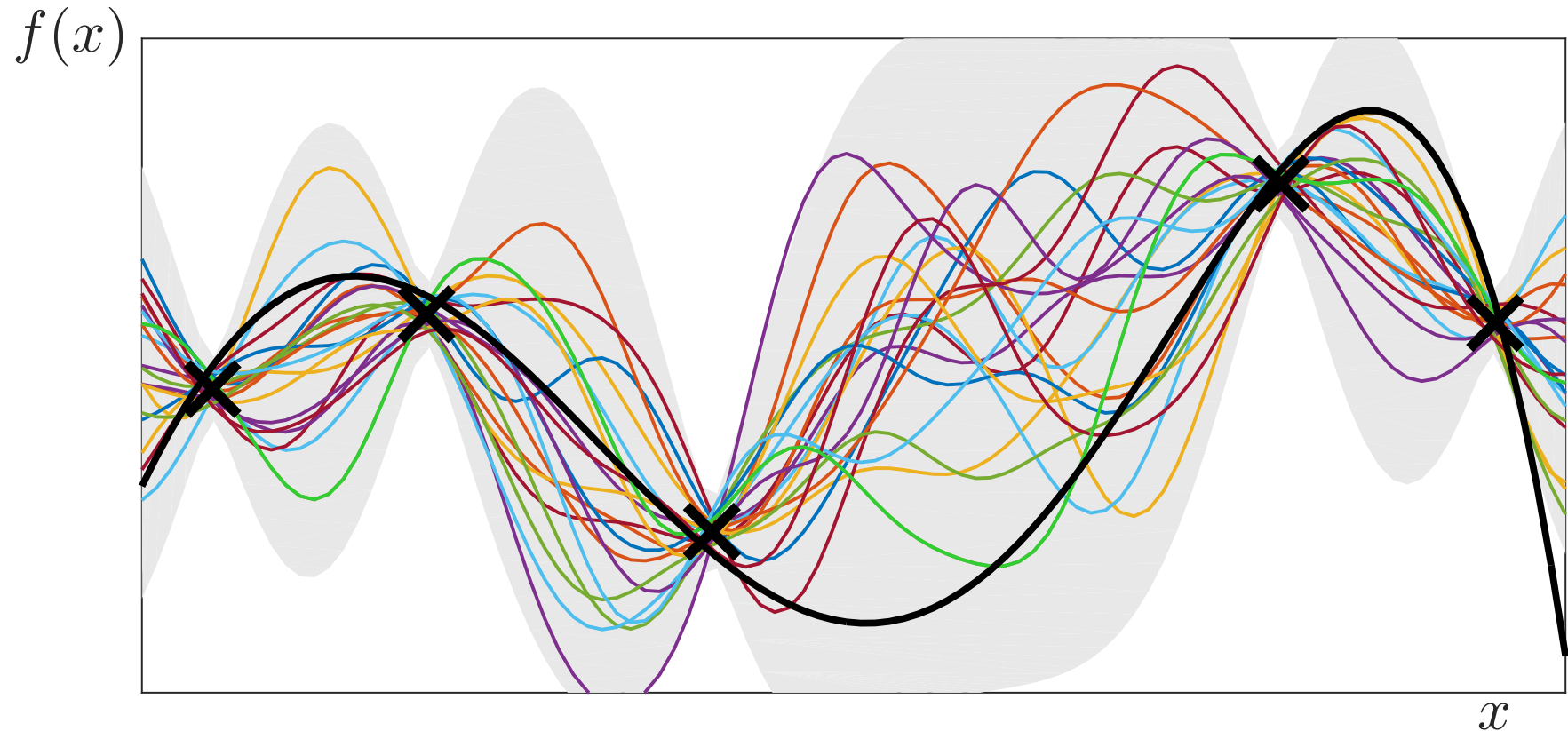


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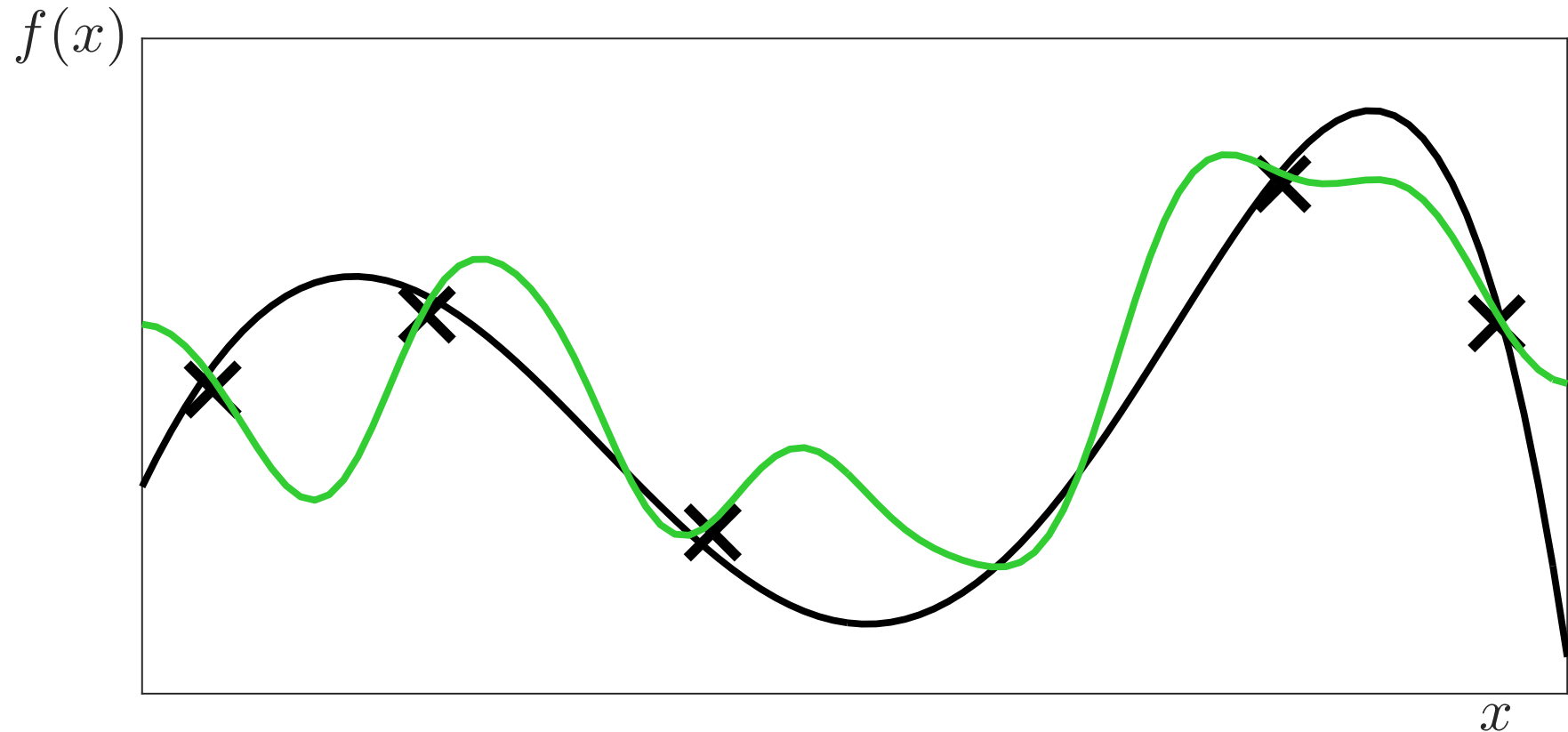
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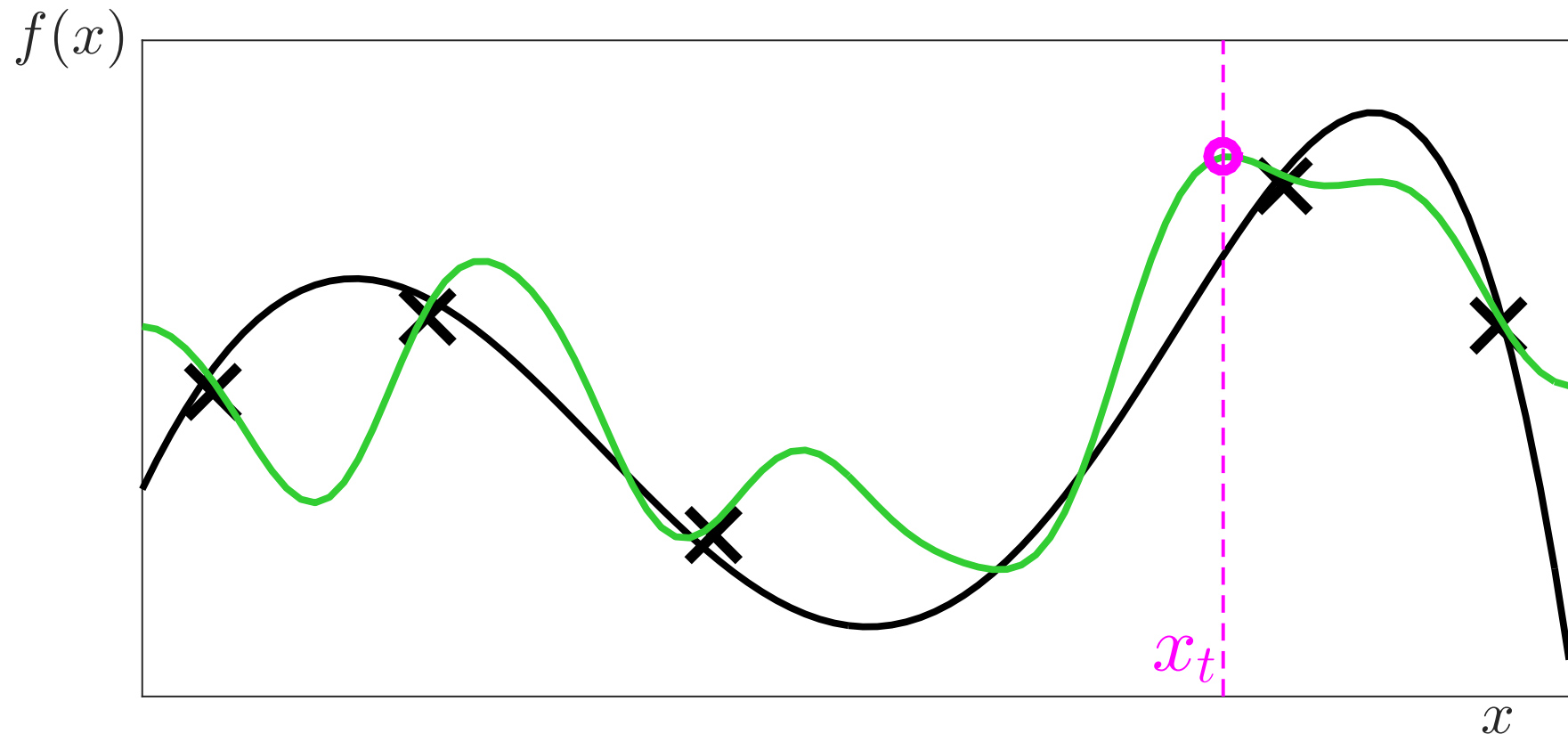
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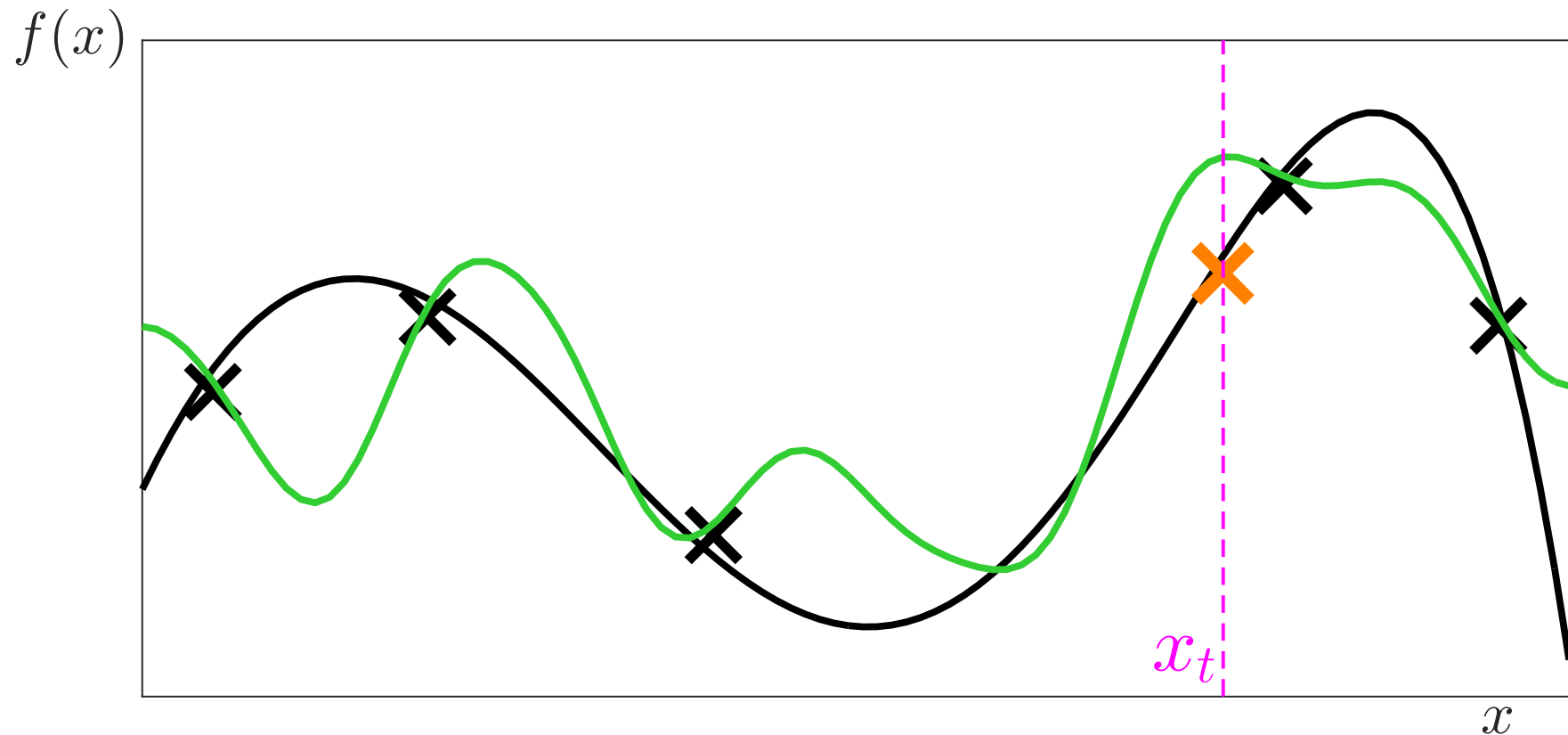
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Reference for more detailed tutorial

- “A Tutorial on Bayesian Optimization of Expensive Cost Functions, with Application to Active User Modeling and Hierarchical Reinforcement Learning” (<https://arxiv.org/pdf/1012.2599.pdf>)

Slides from

- Kirthevasan Kandasamy's talk on "An Introduction to Bayesian Optimisation and (Potential) Applications in Materials Science"
(<https://people.eecs.berkeley.edu/~kandasamy/talks/electrochem-bo-slides.pdf>)
- University of Washington course stat527 recitation Slides 2
(<https://sites.stat.washington.edu/courses/stat527/s14/recitation/Slides2.pptx>)
- CMU S19 10-403 slides on "Bayesian Optimization - Gaussian Processes"
(<https://www.andrew.cmu.edu/course/10-403/slides/S19GaussianProcesses.pdf>)